

Campi vettoriali in \mathbb{R}^2 e \mathbb{R}^3

$$f: A (\subseteq \mathbb{R}) \rightarrow B (\subseteq \mathbb{R})$$

$$\vec{x} \rightarrow \boxed{f} \xrightarrow{\quad} y = f(x)$$

$$f: A (\subseteq \mathbb{R}^m) \rightarrow B (\subseteq \mathbb{R}^m)$$

$$m = m \quad m > 1$$

$$\begin{array}{ccc} x_1 \rightarrow & & \rightarrow z_1 \\ x_2 \rightarrow & \boxed{f} & \rightarrow z_2 \\ \dots & & \dots \\ x_m \rightarrow & & \rightarrow z_m \end{array} \quad m = m$$

$$m = m = 2$$

$$m = m = 3$$

$$\vec{F}: A (\subseteq \mathbb{R}^2) \rightarrow B (\subseteq \mathbb{R}^2)$$

$$\vec{F}(x, y) = (f_1(x, y), f_2(x, y))$$

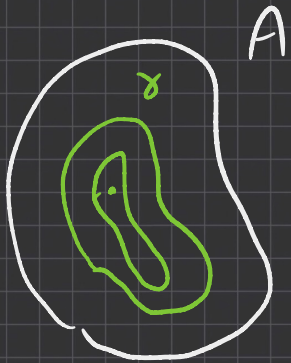
$$\begin{array}{ccc} & \vec{F} & \\ \vec{x} \rightarrow & \boxed{\begin{array}{c} f_1 \\ f_2 \end{array}} & \rightarrow \begin{array}{l} z_1 = f_1(x, y) \\ z_2 = f_2(x, y) \end{array} \\ \vec{y} \rightarrow & & \end{array}$$

Domínio, Rotacionalità, Conservatività

1) Dominio

$$\text{Dom } F = \begin{cases} \text{Dom } f_1 \\ \text{Dom } f_2 \end{cases}$$

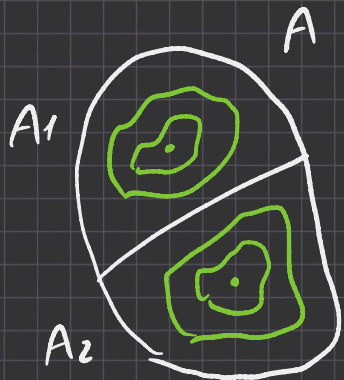
Oss. 1



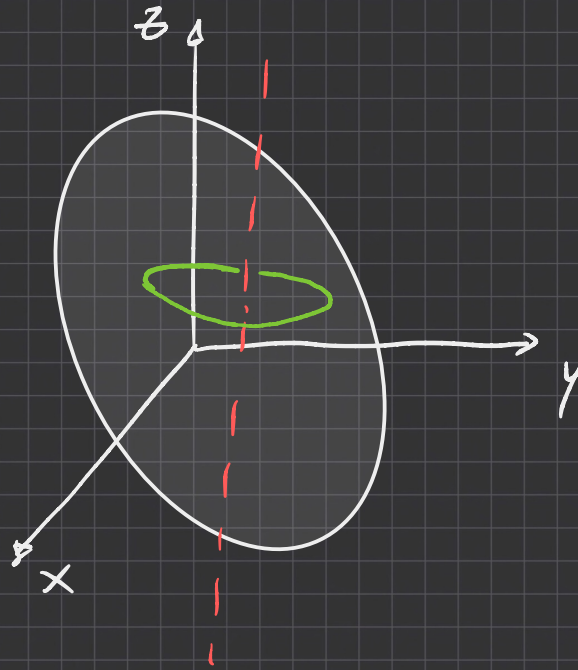
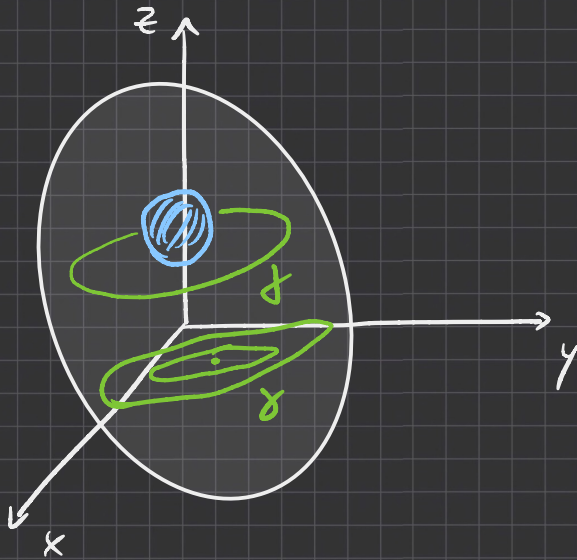
Semplicemente
Connesso



Non è semplicemente
Connesso



$$A = A_1 \cup A_2$$



2) Rotazionalità

$$\text{rot } \vec{F} = \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y}$$

$$\text{rot } \vec{F} = 0 \Rightarrow \frac{\partial f_2}{\partial x} = \frac{\partial f_1}{\partial y} \Rightarrow \vec{F} \text{ è irrotazionale}$$

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$$\underline{F}: A(\subseteq \mathbb{R}^3) \rightarrow \mathbb{R}^3$$

$$\operatorname{rot} \underline{F} = \underline{\nabla} \times \underline{F} = \operatorname{rot} \begin{pmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{pmatrix} = \left(\frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) \underline{i} + \left(\frac{\partial f_1}{\partial z} - \frac{\partial f_3}{\partial x} \right) \underline{j} + \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right) \underline{k}$$

$$\operatorname{rot} \underline{F} = 0 \Rightarrow \begin{aligned} f_{3y} &= f_{2z} \\ f_{1z} &= f_{3x} \\ f_{2x} &= f_{1y} \end{aligned}$$

3) Conservatività

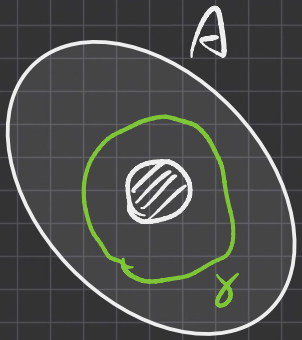
$$U: A(\subseteq \mathbb{R}^2) \rightarrow \mathbb{R} \quad \forall e. \quad \underline{\nabla} U = \underline{F} \Rightarrow \frac{\partial U}{\partial x} = f_1(x, y); \quad \frac{\partial U}{\partial y} = f_2(x, y)$$

Integrale. è condizione necessaria per la conservatività

Oss 3

Se \underline{F} è irrot. su un insieme semplicemente connesso \Rightarrow esiste il potenziale V di $\underline{F} \Rightarrow \underline{F}$ è conservativo

Oss 4

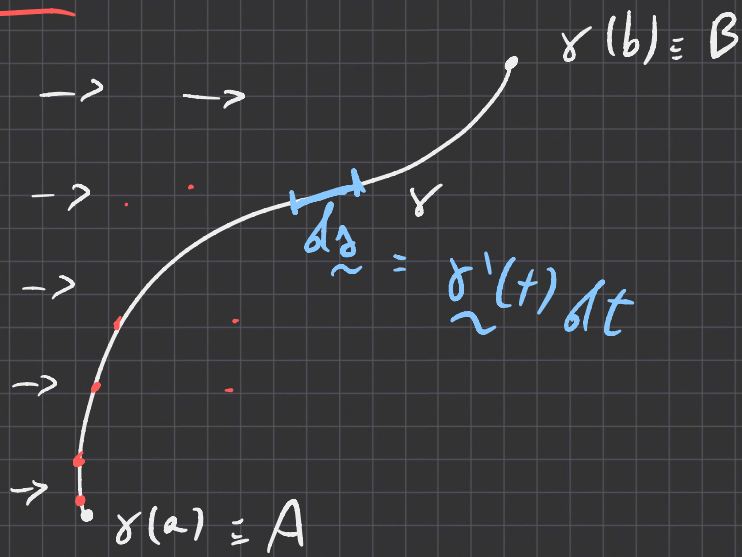


$$\oint_{\gamma} \underline{F} \cdot d\underline{s} = 0$$

Lavoro di un campo vettoriale lungo una curva (integrale curvilineo di II specie)

$$\gamma: [a, b] \rightarrow \mathbb{R}^2, \quad \int_{\gamma} \underline{F} \cdot \underline{d\alpha} = \int_a^b \underline{F}(\underline{\gamma}(t)) \cdot \underline{\gamma}'(t) dt$$

Obs 5



$$dL = \underline{F} \cdot \underline{d\alpha}$$

$$dL = \underline{F} \cdot \underline{d\alpha} = \underline{F} \cdot \underline{\gamma}'(t) dt$$

$$L = \int_a^b \underline{F}(\underline{\gamma}(t)) \cdot \underline{\gamma}'(t) dt$$

$$\underline{F}(x, y)$$

Oss 6

Se $\underline{\tilde{F}}$ è conservativo il lavoro svolto da $\underline{\tilde{F}}$ per passare dal punto A al punto B è dato dalla diff. di potenziale:

$$L_{AB} = \int_a^b \underline{\tilde{F}}(\underline{\gamma}(t)) \cdot \underline{\gamma}'(t) dt = U(B) - U(A) = U(\gamma(b)) - U(\gamma(a))$$